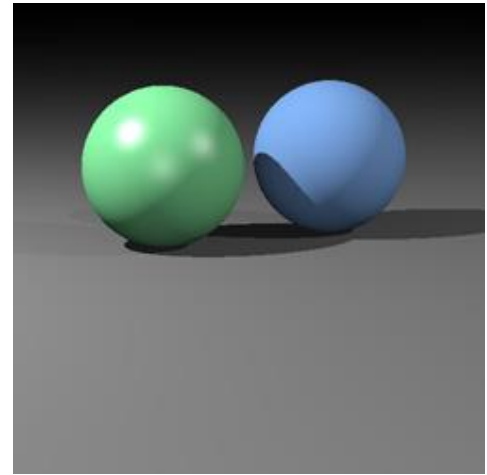
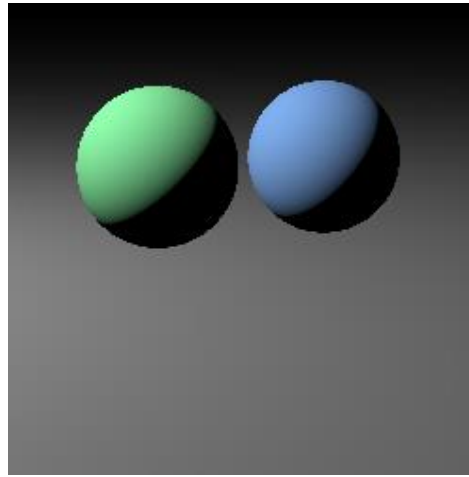


Ray Tracing

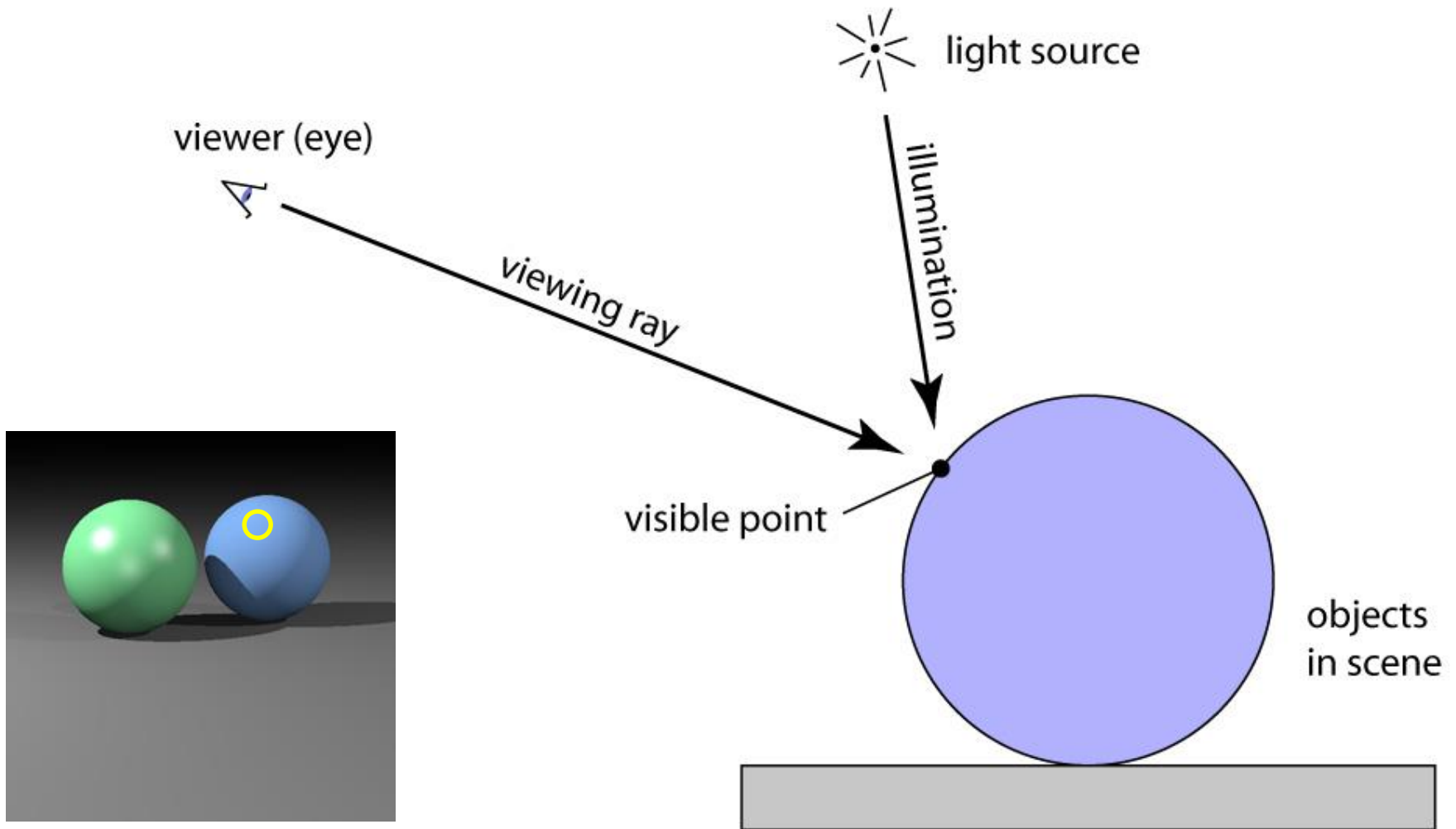
Lecture 4

Ray Tracing

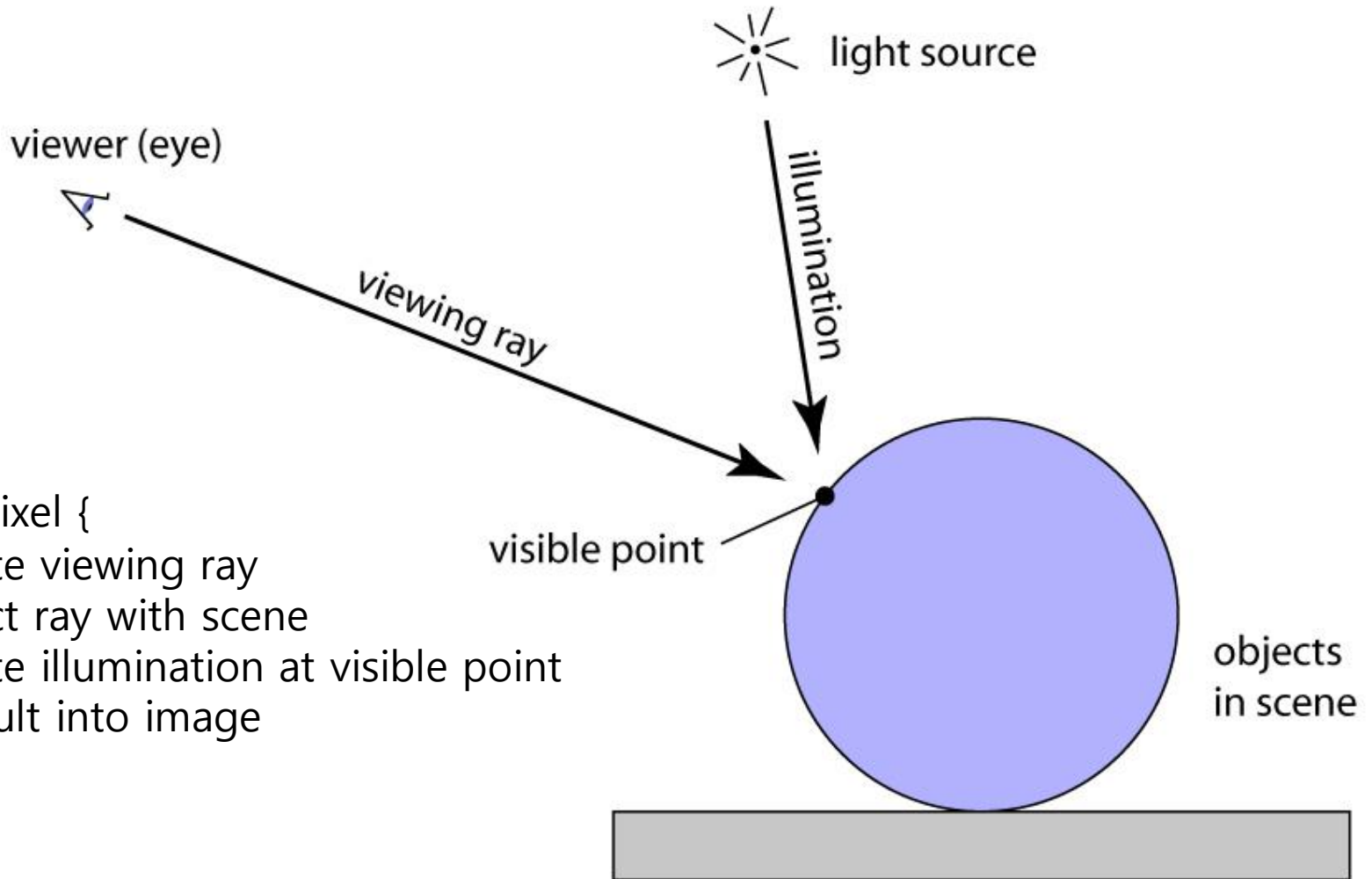
- PA#1



Ray tracing idea



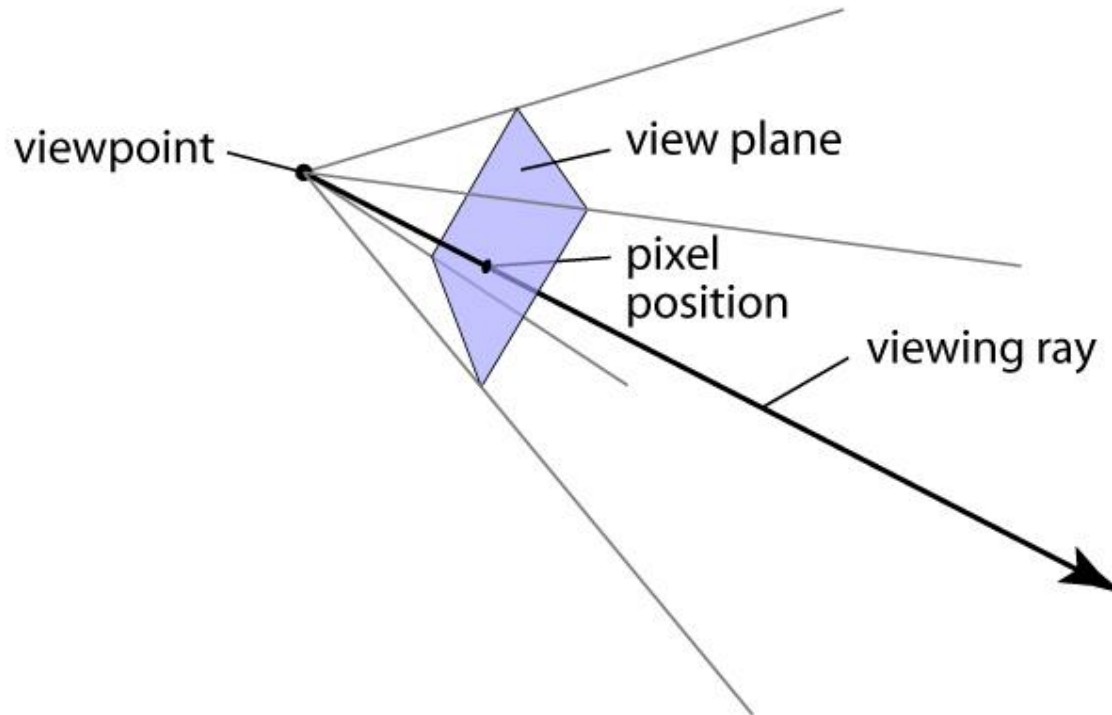
Ray tracing algorithm



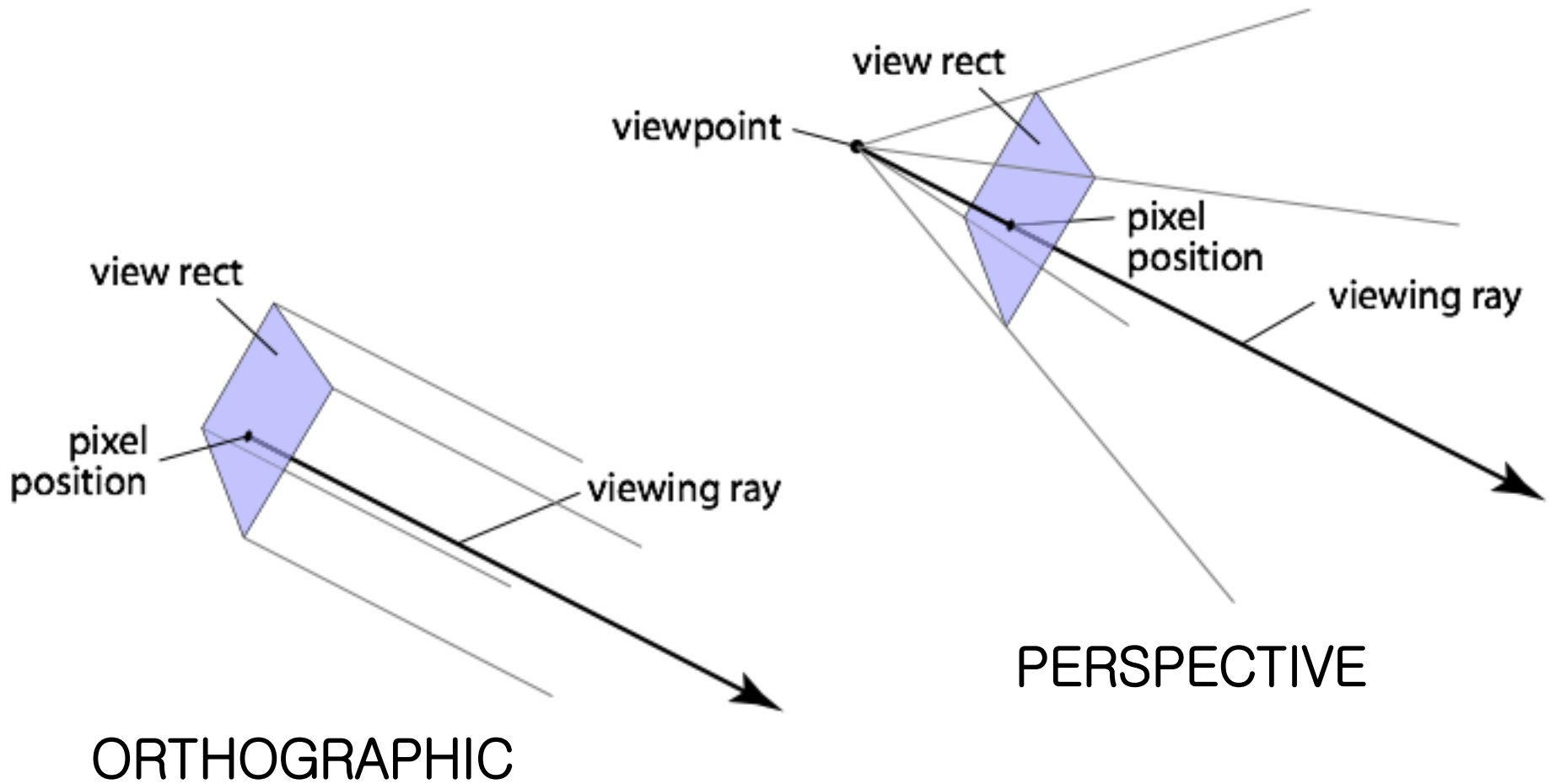
```
for each pixel {  
  compute viewing ray  
  intersect ray with scene  
  compute illumination at visible point  
  put result into image  
}
```

Generating eye rays

- Use window analogy directly

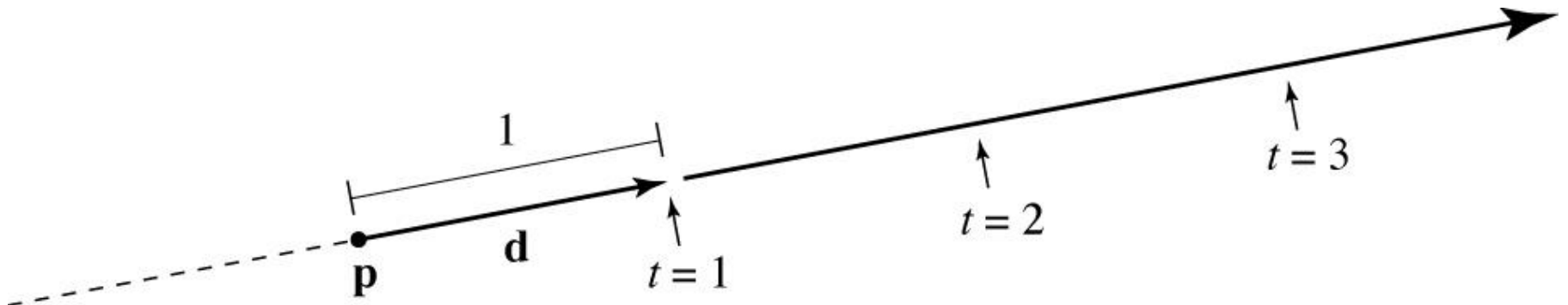


Generating eye rays



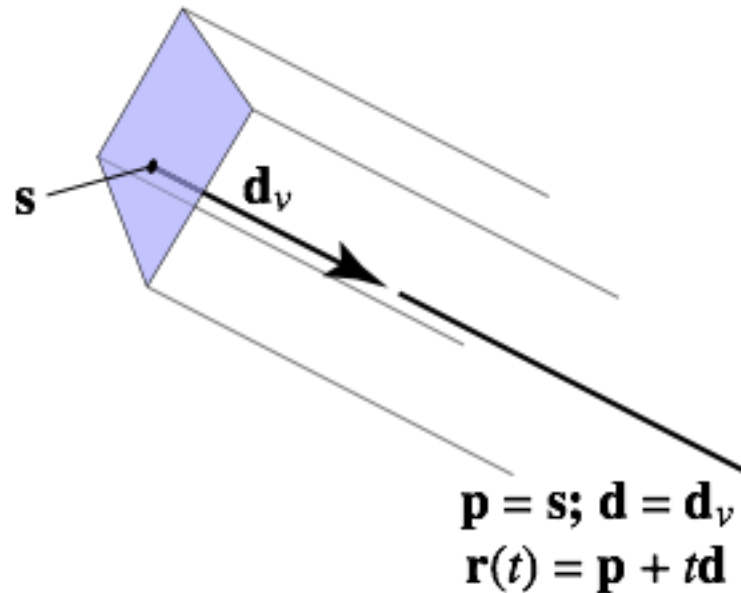
Ray: a half line

- Standard representation: point \mathbf{p} and direction \mathbf{d}
 $\mathbf{r}(t) = \mathbf{p} + t\mathbf{d}$
 - this is a *parametric equation* for the line
 - lets us directly generate the points on the line
 - if we restrict to $t > 0$ then we have a ray
 - note replacing \mathbf{d} with $a\mathbf{d}$ doesn't change ray ($a > 0$)



Generating eye rays—orthographic

- Just need to compute the view plane point \mathbf{s} :



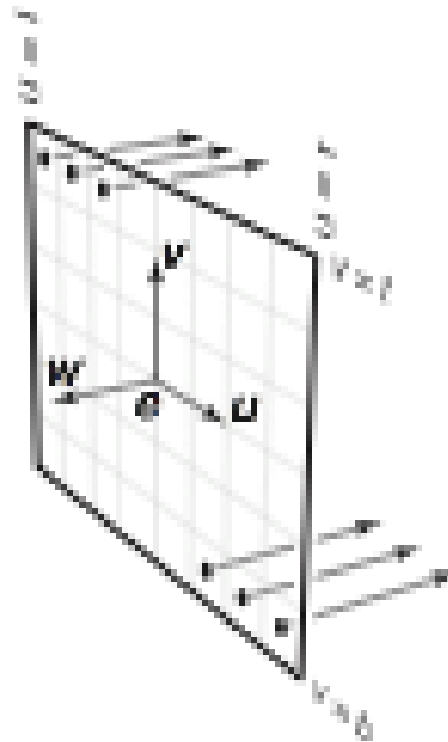
– but where exactly is the view rectangle?

Generating eye rays—orthographic

$$\mathbf{s} = \mathbf{e} + u\mathbf{u} + v\mathbf{v}$$

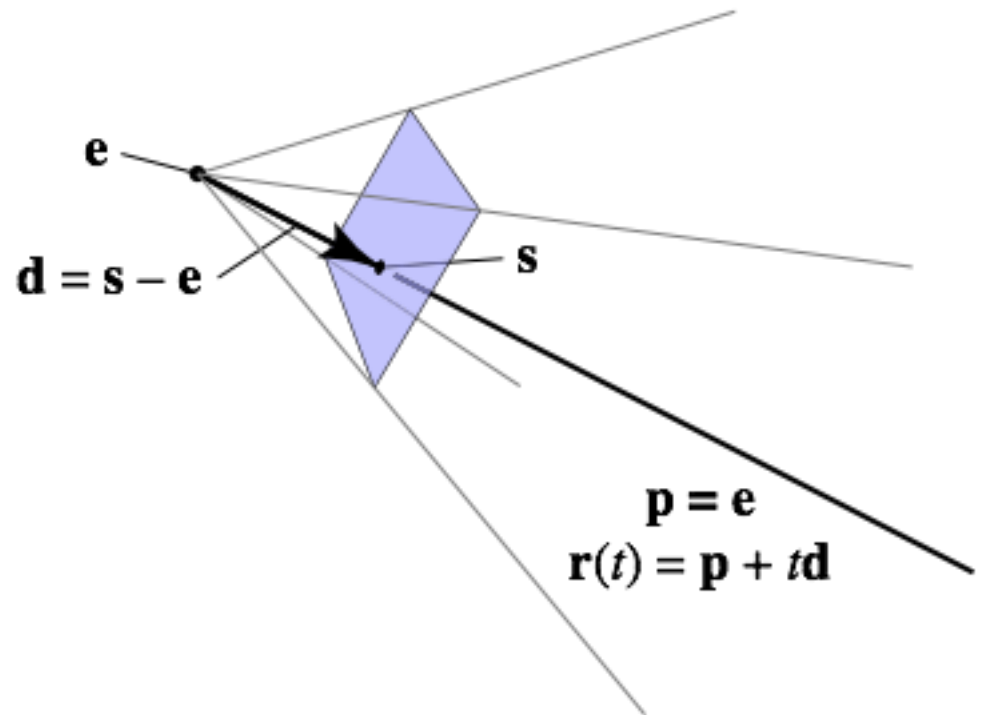
$$\mathbf{p} = \mathbf{s}; \mathbf{d} = -\mathbf{w}$$

$$\mathbf{r}(t) = \mathbf{p} + t\mathbf{d}$$



Generating eye rays—perspective

- Distance is important: “focal length” of camera
 - ray origin always \mathbf{e}
 - ray direction controlled by \mathbf{s}



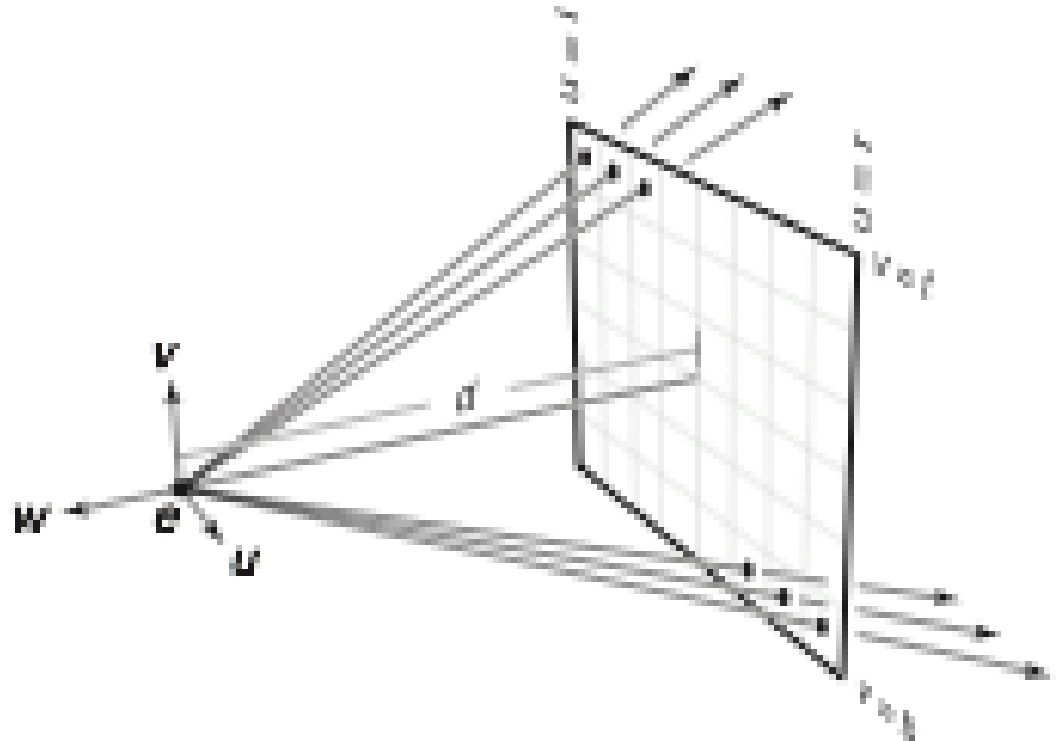
Generating eye rays—perspective

- Compute \mathbf{s} in the same way; just subtract $d\mathbf{w}$
 - coordinates of \mathbf{s} are $(u, v, -d)$

$$\mathbf{s} = \mathbf{e} + u\mathbf{u} + v\mathbf{v} - d\mathbf{w}$$

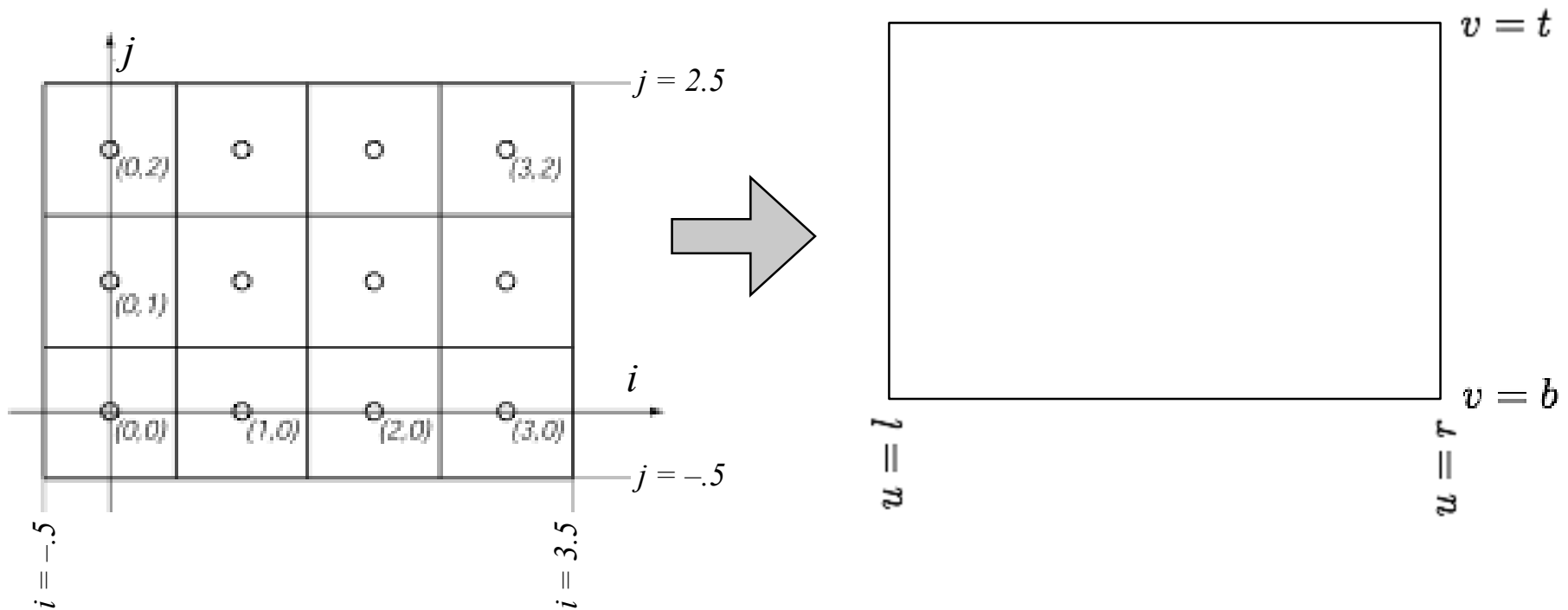
$$\mathbf{p} = \mathbf{e}; \mathbf{d} = \mathbf{s} - \mathbf{e}$$

$$\mathbf{r}(t) = \mathbf{p} + t\mathbf{d}$$



Pixel-to-image mapping

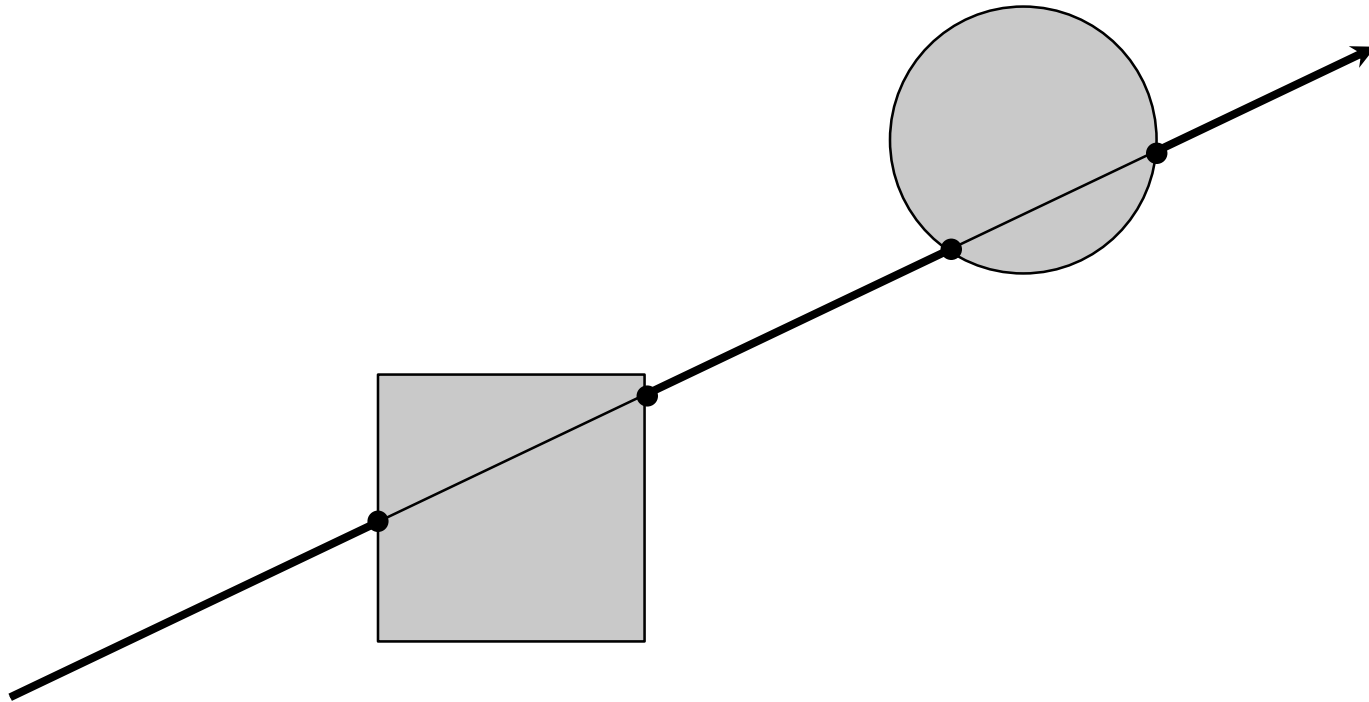
- One last detail: (u, v) coords of a pixel



$$u = l + (r - l)(i + 0.5)/n_x$$

$$v = b + (t - b)(j + 0.5)/n_y$$

Ray intersection



Ray-sphere intersection: algebraic

- Condition 1: intersection point \mathbf{r} is on ray

$$\mathbf{r}(t) = \mathbf{p} + t\mathbf{d}$$

- Condition 2: point is on sphere
 - assume unit sphere; see Shirley or notes for general

$$\|\mathbf{x}\| = 1 \Leftrightarrow \|\mathbf{x}\|^2 = 1$$

$$f(\mathbf{x}) = \mathbf{x} \cdot \mathbf{x} - 1 = 0$$

- Substitute:

$$(\mathbf{p} + t\mathbf{d}) \cdot (\mathbf{p} + t\mathbf{d}) - 1 = 0$$

- this is a quadratic equation in t

Ray-sphere intersection: algebraic

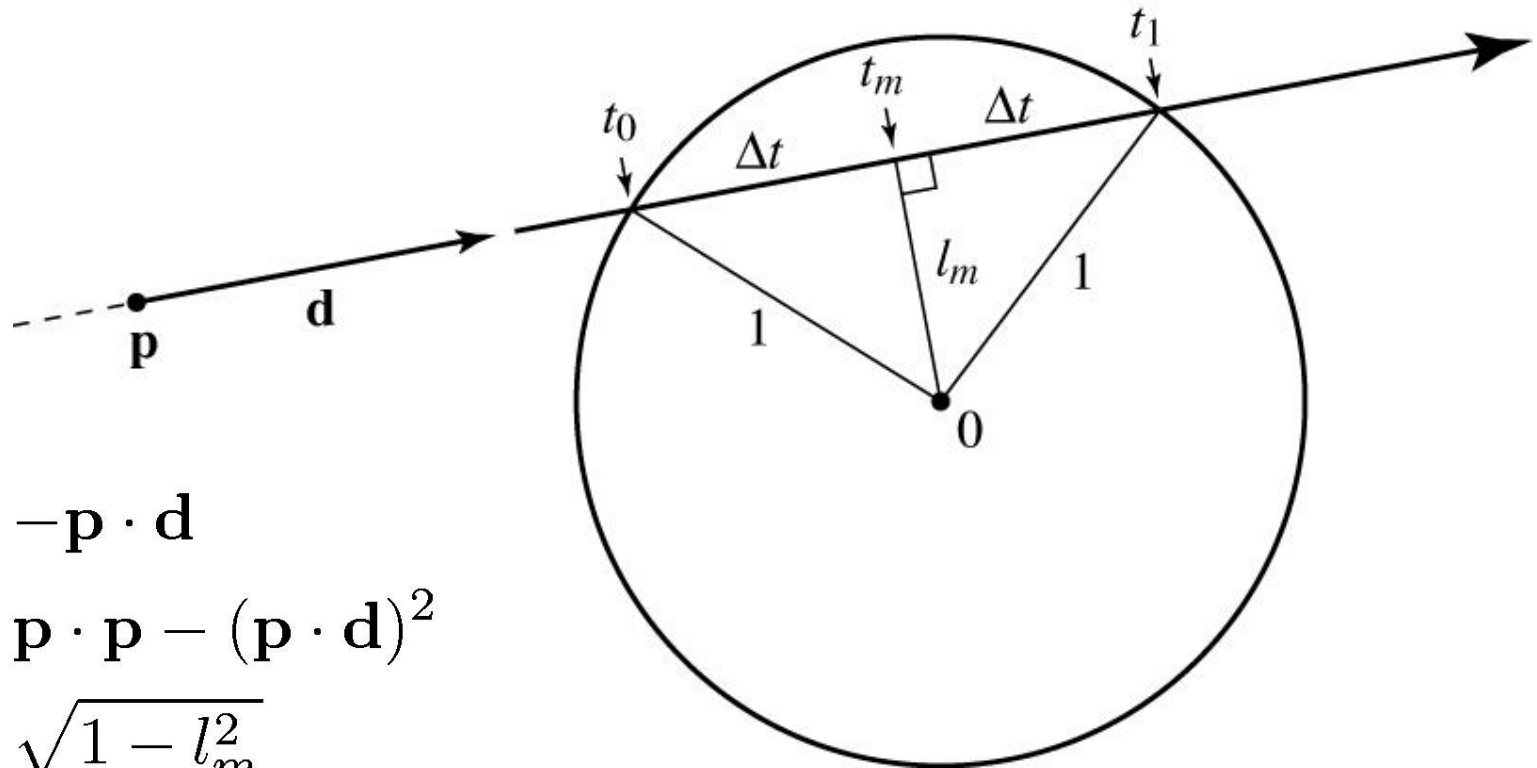
- Solution for t by quadratic formula:

$$t = \frac{-\mathbf{d} \cdot \mathbf{p} \pm \sqrt{(\mathbf{d} \cdot \mathbf{p})^2 - (\mathbf{d} \cdot \mathbf{d})(\mathbf{p} \cdot \mathbf{p} - 1)}}{\mathbf{d} \cdot \mathbf{d}}$$

$$t = -\mathbf{d} \cdot \mathbf{p} \pm \sqrt{(\mathbf{d} \cdot \mathbf{p})^2 - \mathbf{p} \cdot \mathbf{p} + 1}$$

- simpler form holds when \mathbf{d} is a unit vector

Ray-sphere intersection: geometric



$$t_m = -\mathbf{p} \cdot \mathbf{d}$$

$$l_m^2 = \mathbf{p} \cdot \mathbf{p} - (\mathbf{p} \cdot \mathbf{d})^2$$

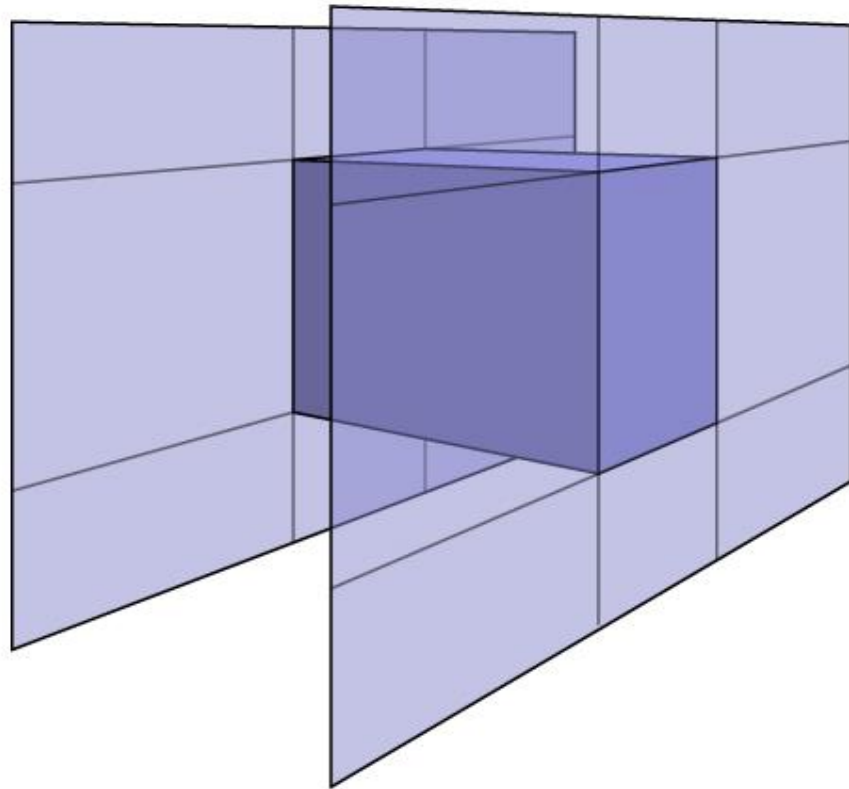
$$\Delta t = \sqrt{1 - l_m^2}$$

$$= \sqrt{(\mathbf{p} \cdot \mathbf{d})^2 - \mathbf{p} \cdot \mathbf{p} + 1}$$

$$t_{0,1} = t_m \pm \Delta t = -\mathbf{p} \cdot \mathbf{d} \pm \sqrt{(\mathbf{p} \cdot \mathbf{d})^2 - \mathbf{p} \cdot \mathbf{p} + 1}$$

Ray-box intersection

- Could intersect with 6 faces individually
- Better way: box is the intersection of 3 slabs



Ray-slab intersection

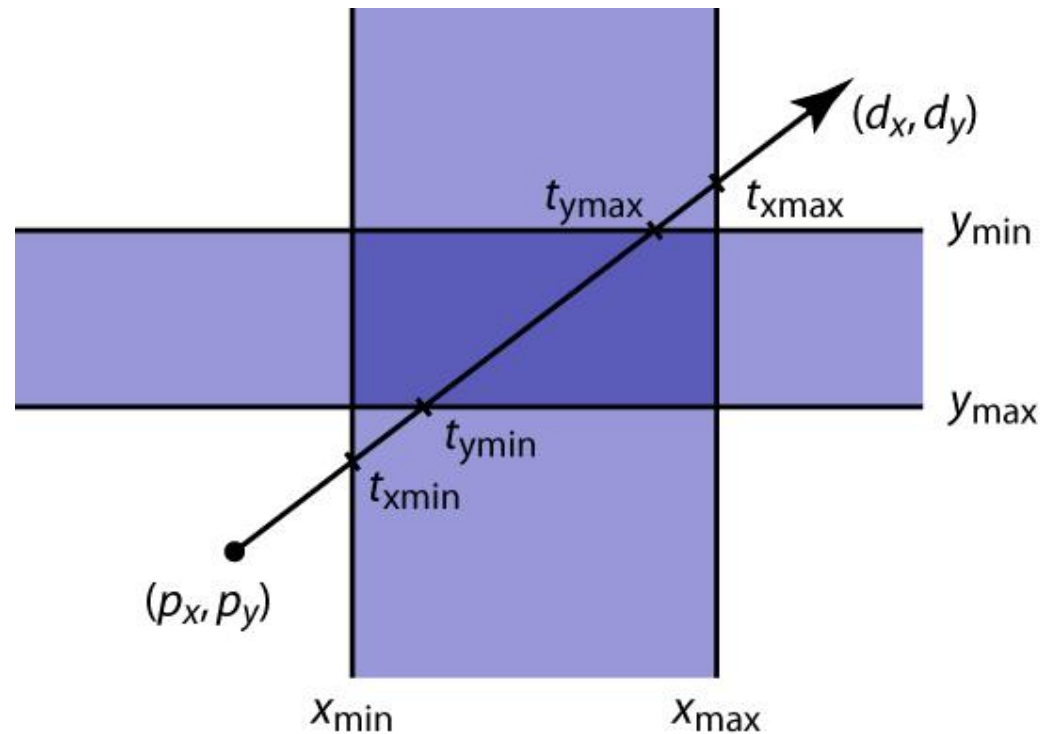
- 2D example
- 3D is the same!

$$p_x + t_{x\min} d_x = x_{\min}$$

$$t_{x\min} = (x_{\min} - p_x) / d_x$$

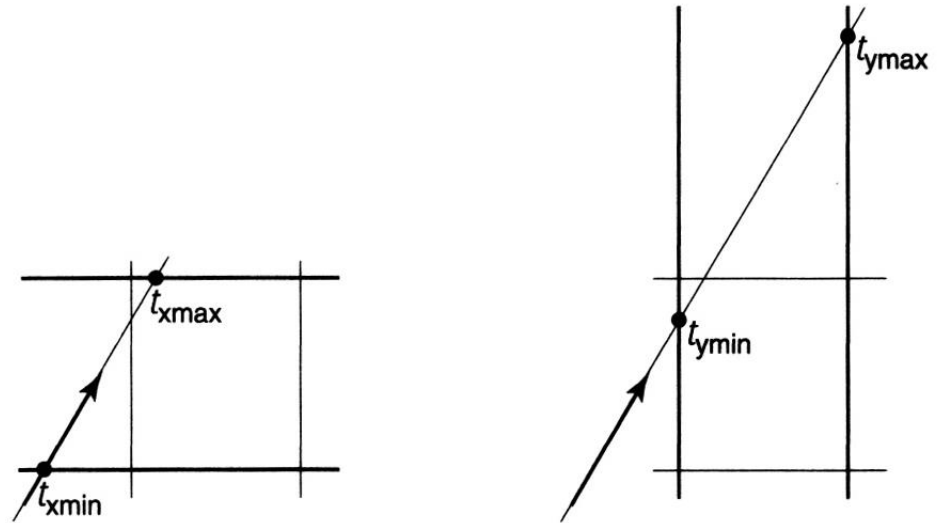
$$p_y + t_{y\min} d_y = y_{\min}$$

$$t_{y\min} = (y_{\min} - p_y) / d_y$$



Intersecting intersections

- Each intersection is an interval
- Want last entry point and first exit point



$$t_{\min} = \max(t_{x\min}, t_{y\min})$$

$$t_{\max} = \min(t_{x\max}, t_{y\max})$$

$$t \in [t_{x\min}, t_{x\max}]$$

$$t \in [t_{y\min}, t_{y\max}]$$

$$t \in [t_{x\min}, t_{x\max}] \cap [t_{y\min}, t_{y\max}]$$

Shirley fig. 10.16

Ray-triangle intersection

- Condition 1: point is on ray

$$\mathbf{r}(t) = \mathbf{p} + t\mathbf{d}$$

- Condition 2: point is on plane

$$(\mathbf{x} - \mathbf{a}) \cdot \mathbf{n} = 0$$

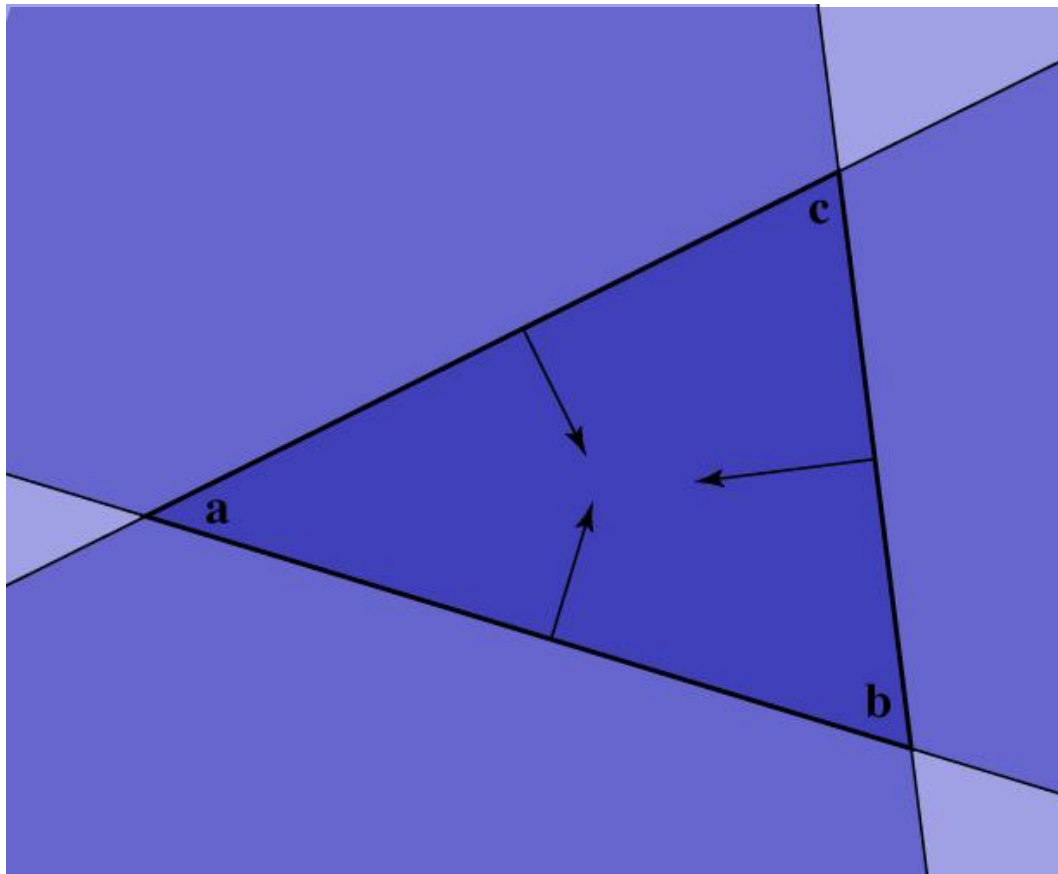
- Condition 3: point is on the inside of all three edges
- First solve 1&2 (ray-plane intersection)
 - substitute and solve for t :

$$(\mathbf{p} + t\mathbf{d} - \mathbf{a}) \cdot \mathbf{n} = 0$$

$$t = \frac{(\mathbf{a} - \mathbf{p}) \cdot \mathbf{n}}{\mathbf{d} \cdot \mathbf{n}}$$

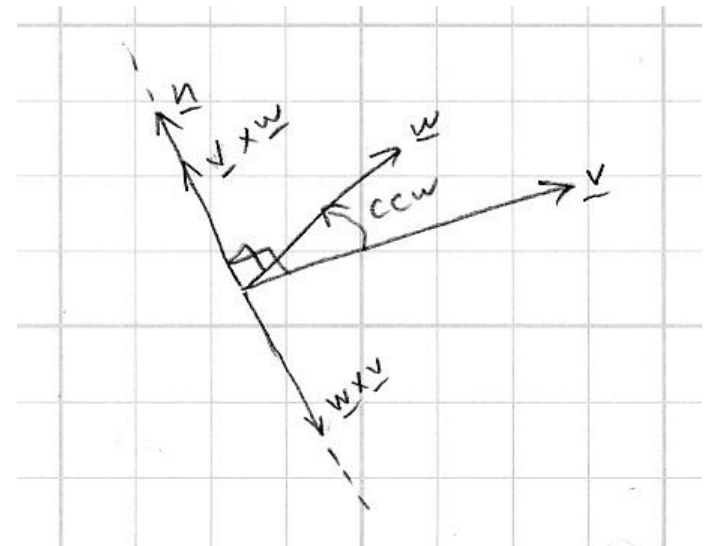
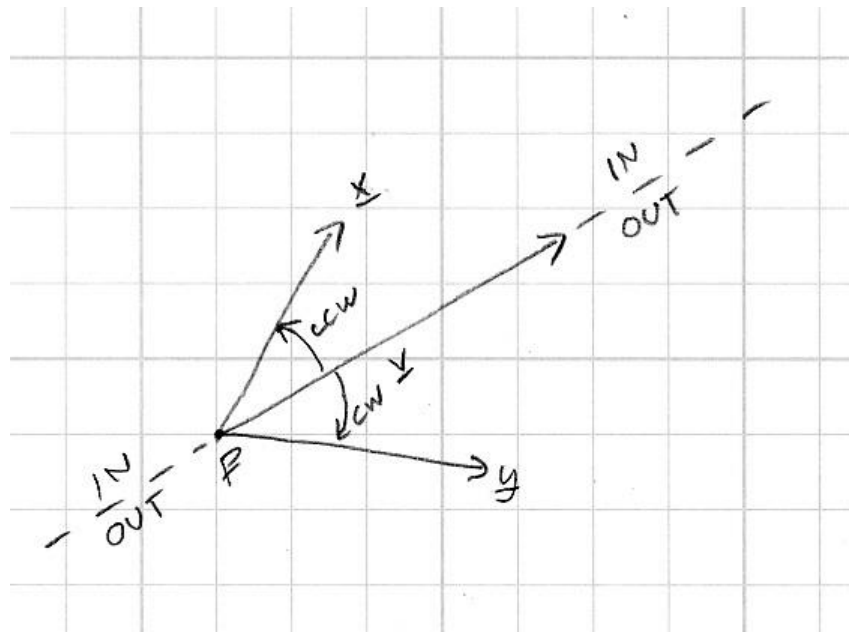
Ray-triangle intersection

- In plane, triangle is the intersection of 3 half spaces



Inside-edge test

- Need outside vs. inside
- Reduce to clockwise vs. counterclockwise
 - vector of edge to vector to x
- Use cross product to decide



Ray-triangle intersection

$$(\mathbf{b} - \mathbf{a}) \times (\mathbf{x} - \mathbf{a}) \cdot \mathbf{n} > 0$$

$$(\mathbf{c} - \mathbf{b}) \times (\mathbf{x} - \mathbf{b}) \cdot \mathbf{n} > 0$$

$$(\mathbf{a} - \mathbf{c}) \times (\mathbf{x} - \mathbf{c}) \cdot \mathbf{n} > 0$$

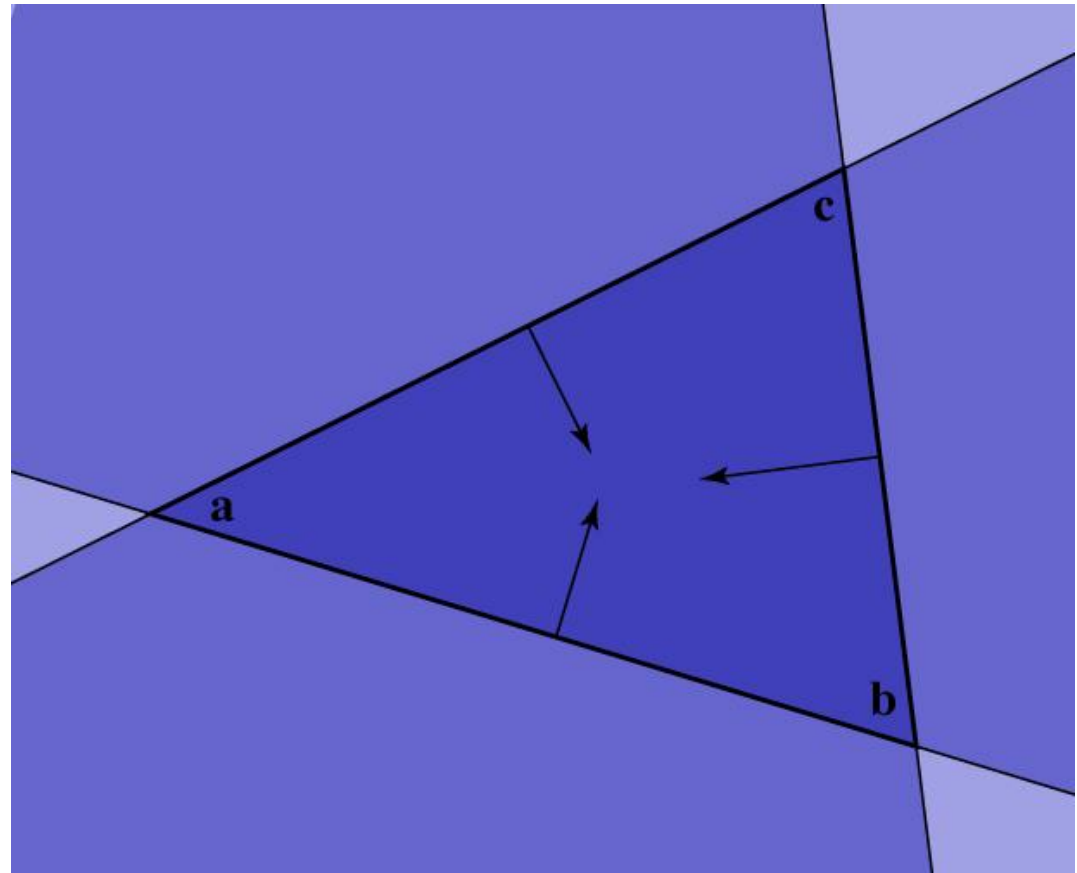
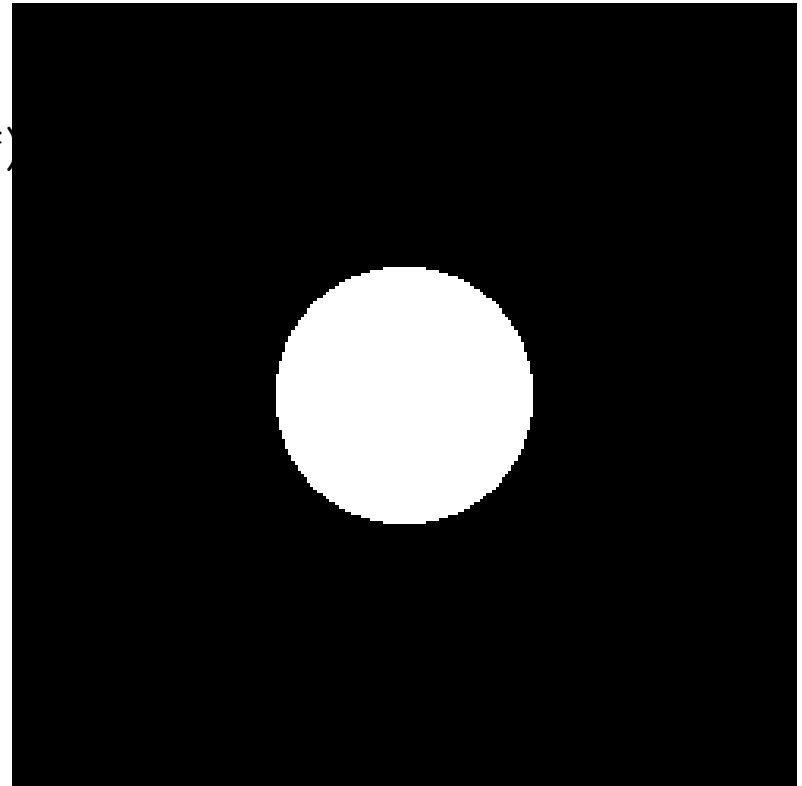


Image so far

- With eye ray generation and sphere intersection

```
Surface s = new Sphere((0.0, 0.0, 0.0), 1.0);  
for 0 <= iy < ny  
  for 0 <= ix < nx {  
    ray = camera.getRay(ix, iy);  
    hitSurface, t = s.intersect(ray, 0, +inf);  
    if hitSurface is not null  
      image.set(ix, iy, white);  
  }
```



Intersection against many shapes

```
Group.intersect (ray, tMin, tMax) {
    tBest = +inf; firstSurface = null;
    for surface in surfaceList {
        hitSurface, t = surface.intersect(ray, tMin, tBest);
        if hitSurface is not null {
            tBest = t;
            firstSurface = hitSurface;
        }
    }
    return hitSurface, tBest;
}
```

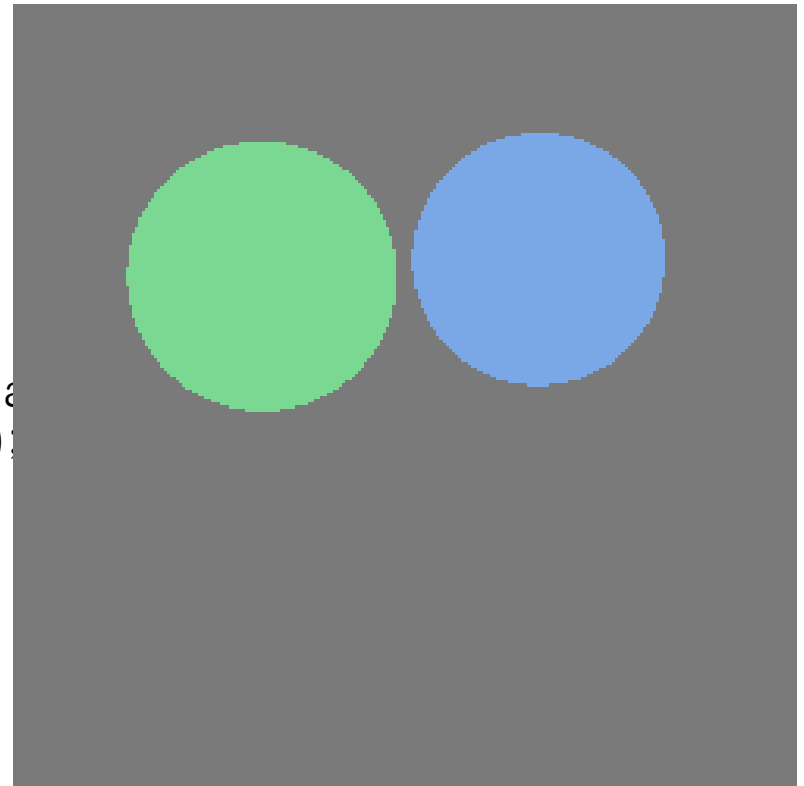
Image so far

- With eye ray generation and scene intersection

```
for 0 <= iy < ny
  for 0 <= ix < nx {
    ray = camera.getRay(ix, iy);
    c = scene.trace(ray, 0, +inf);
    image.set(ix, iy, c);
  }
```

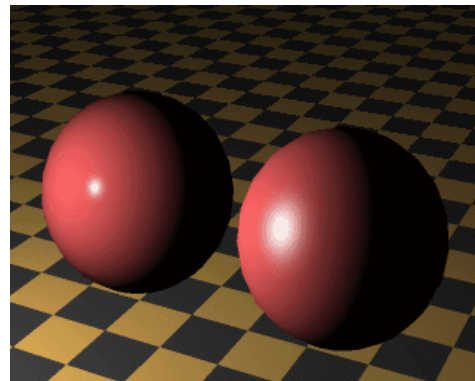
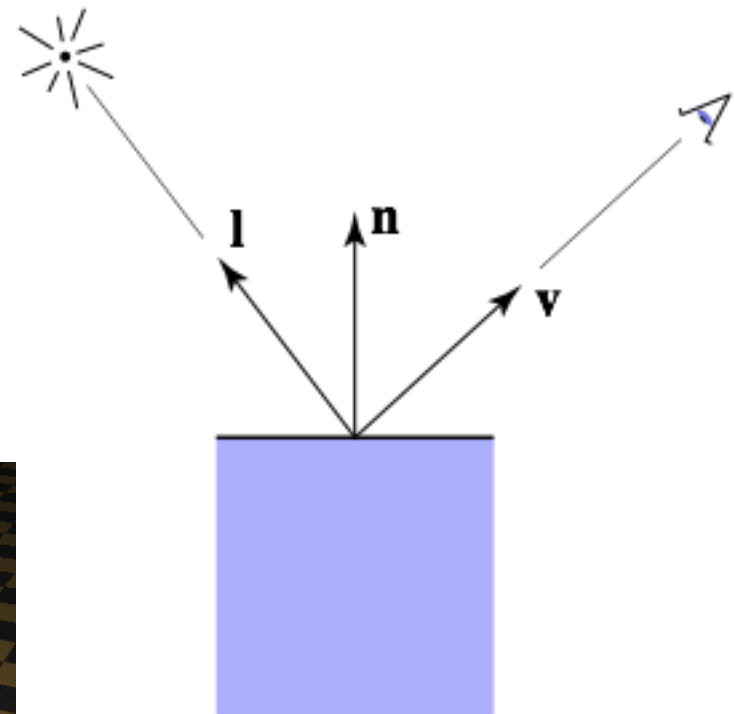
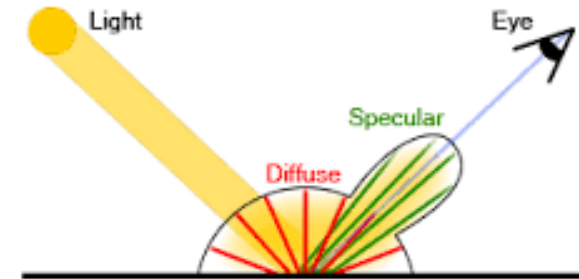
...

```
Scene.trace(ray, tMin, tMax) {
  surface, t = surfs.intersect(ray, tMin, tMax);
  if (surface != null) return surface.color();
  else return black;
}
```



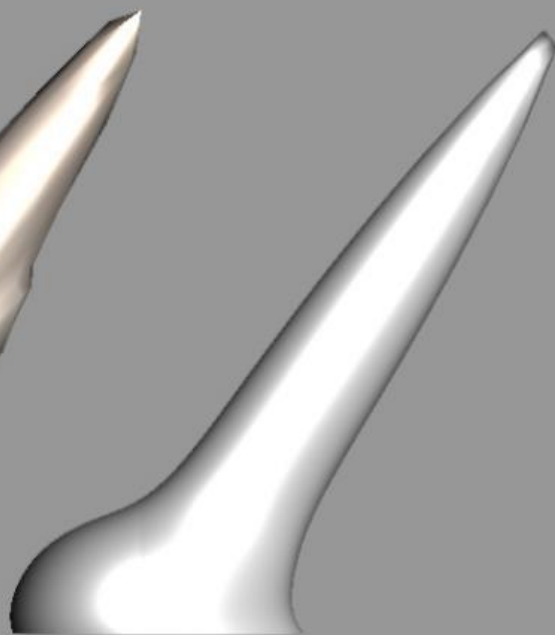
Shading

- Compute light reflected toward camera
- Inputs:
 - eye direction
 - light direction (for each of many lights)
 - surface normal
 - surface parameters (color, shininess, ...)

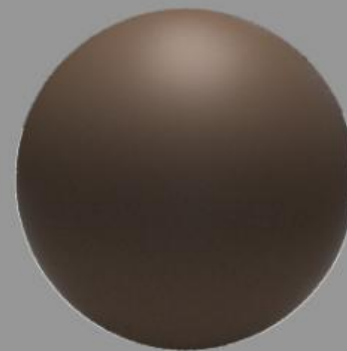




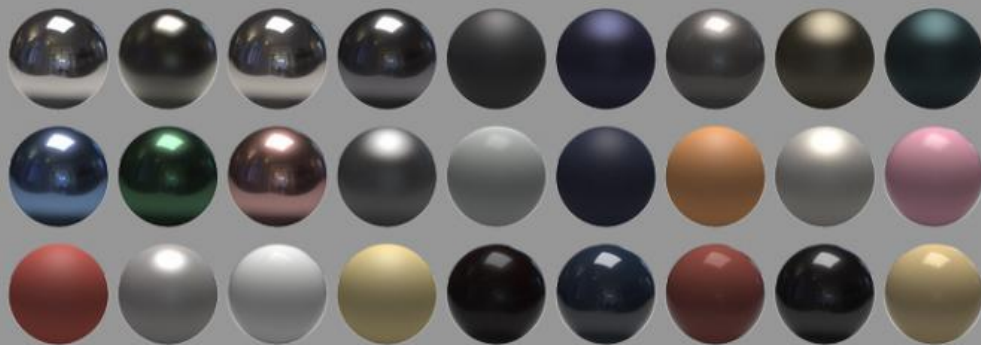
measured BRDF



approximated with
PBR layered Material



Mantra render



all Presets are either "eyeballed" from measured BRDF
or physical measurement of IOR (Glass) and
komplex IOR (Metals)

Diffuse reflection

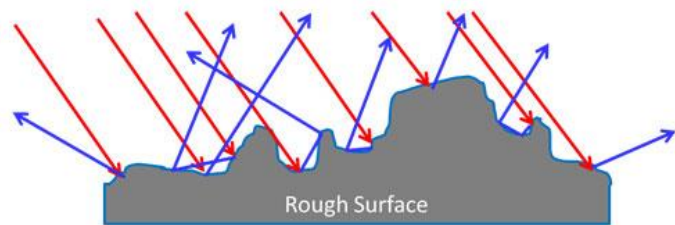
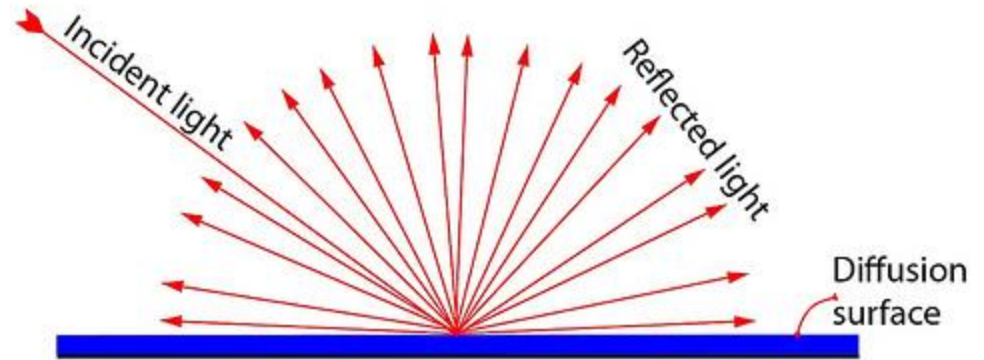
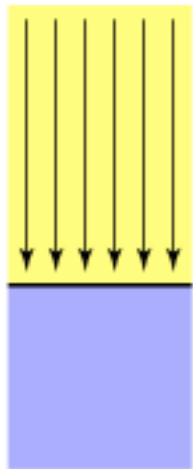


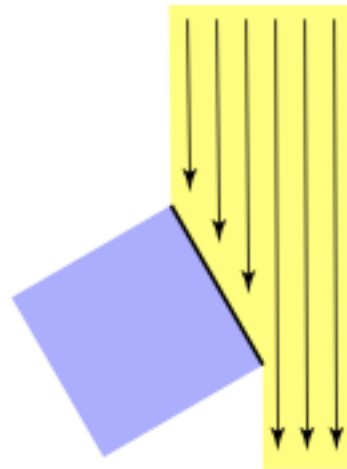
Diagram showing "Diffuse Reflection"



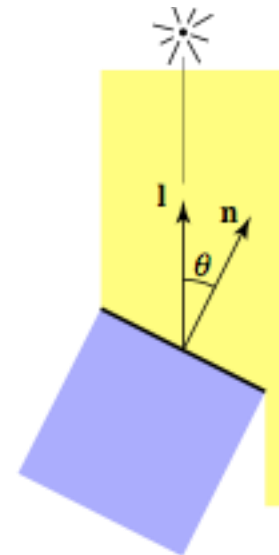
Incident light striking a perfect 'Diffusion Surface' creates a hemisphere of even illumination around the strike point.



Top face of cube receives a certain amount of light

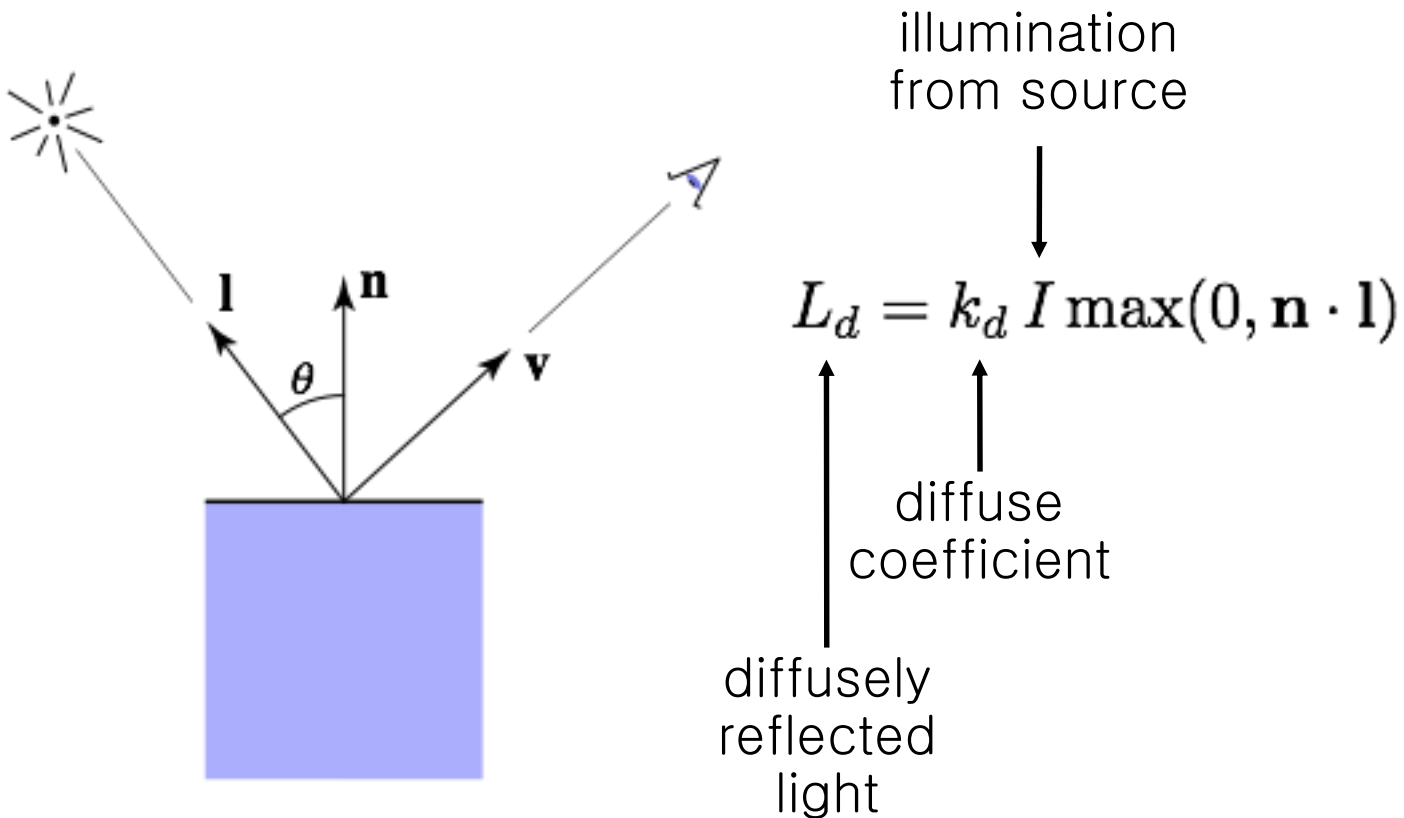


Top face of 60° rotated cube intercepts half the light



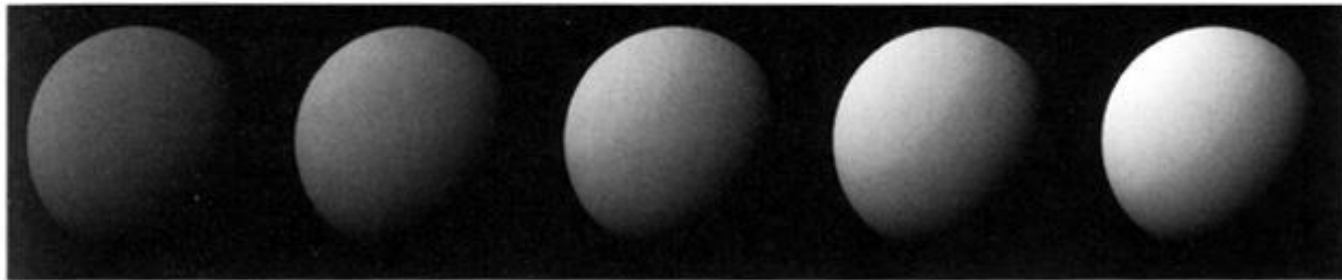
In general, light per unit area is proportional to $\cos \theta = l \cdot n$

Lambertian shading



Lambertian shading

- Produces matte appearance



$k_d \longrightarrow$

[Foley et al.]

Diffuse shading

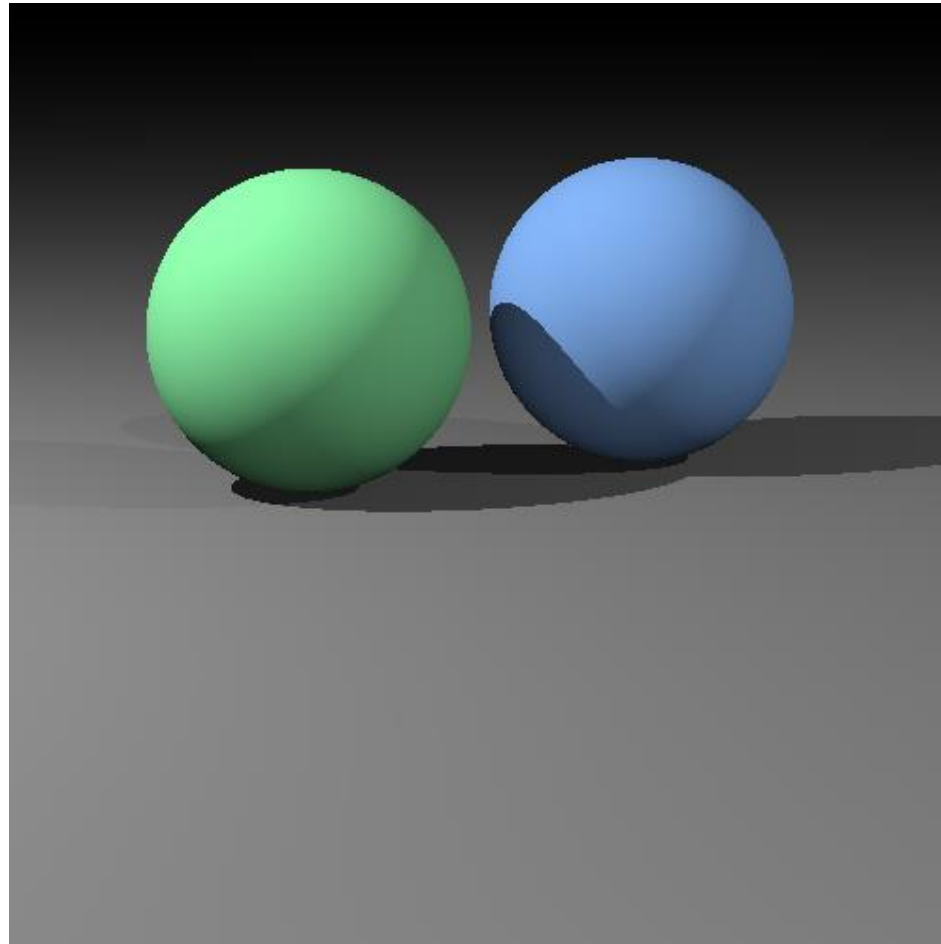
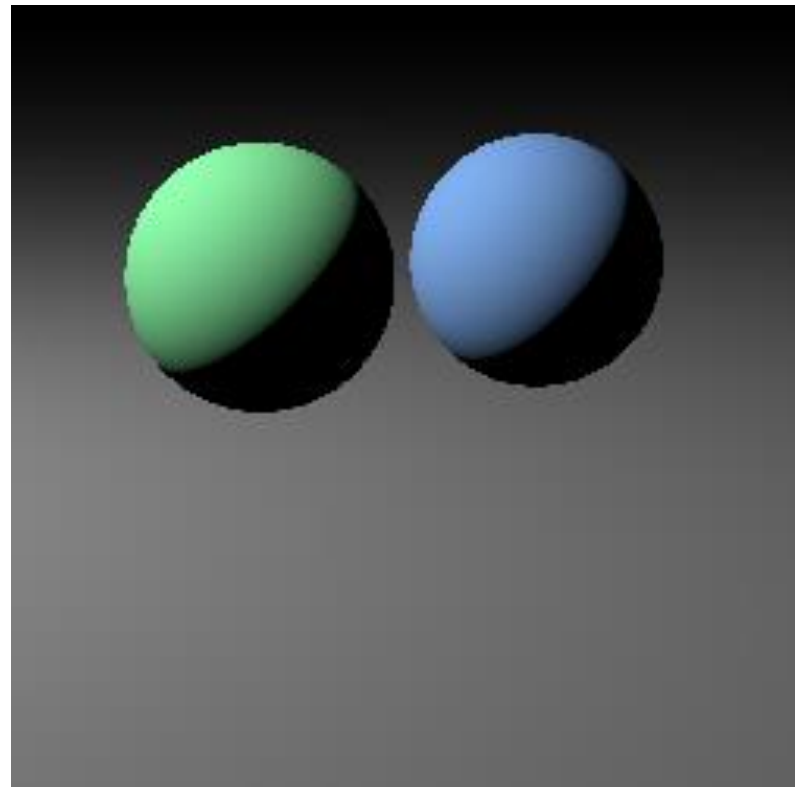


Image so far

```
Scene.trace(Ray ray, tMin, tMax) {  
    surface, t = hit(ray, tMin, tMax);  
    if surface is not null {  
        point = ray.evaluate(t);  
        normal = surface.getNormal(point);  
        return surface.shade(ray, point,  
            normal, light);  
    }  
    else return backgroundColor;  
}
```

...

```
Surface.shade(ray, point, normal, light) {  
    v = -normalize(ray.direction);  
    l = normalize(light.pos - point);  
    // compute shading  
}
```

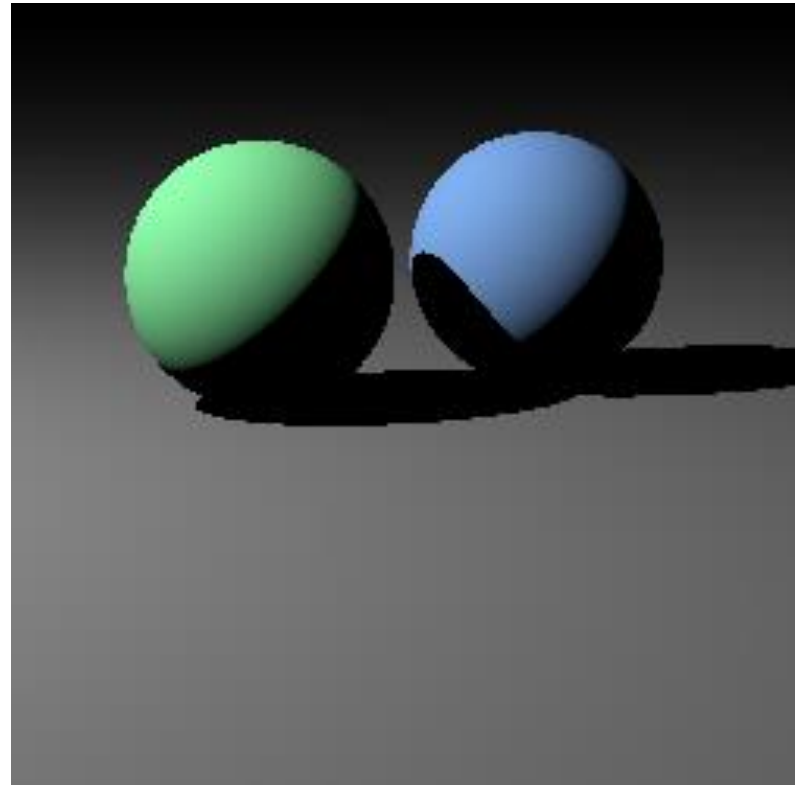


Shadows

- Surface is only illuminated if nothing blocks its view of the light.
- With ray tracing it's easy to check
 - just intersect a ray with the scene!

Image so far

```
Surface.shade(ray, point, normal, light) {  
    shadRay = (point, light.pos - point);  
    if (shadRay not blocked) {  
        v = -normalize(ray.direction);  
        l = normalize(light.pos - point);  
        // compute shading  
    }  
    return black;  
}
```

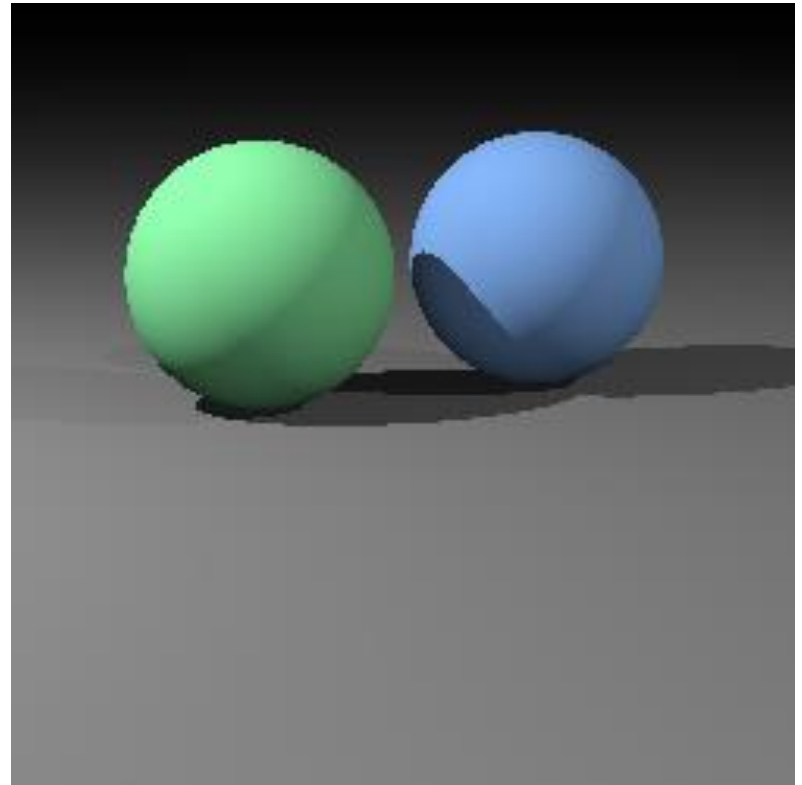


Multiple lights

- Important to fill in black shadows
- Just loop over lights, add contributions
- Ambient shading
 - black shadows are not really right
 - add a constant “ambient” color to the shading...

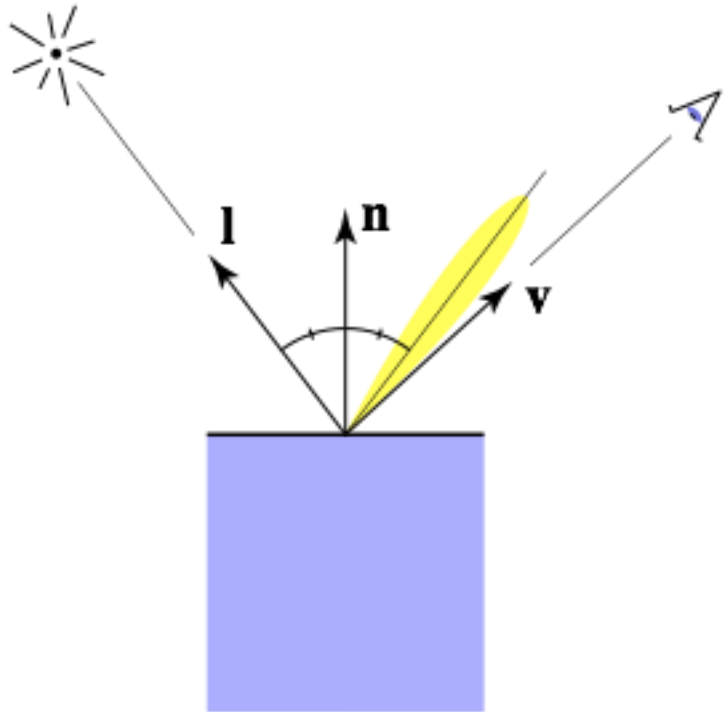
Image so far

```
shade(ray, point, normal, lights) {  
    result = ambient;  
    for light in lights {  
        if (shadow ray not blocked) {  
            result += shading contribution;  
        }  
    }  
    return result;  
}
```



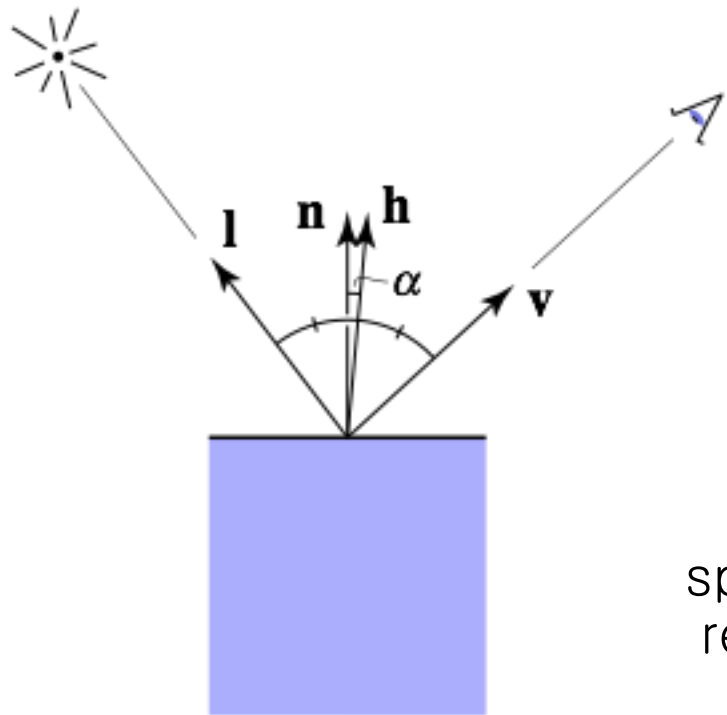
Specular shading (Blinn–Phong)

- Intensity depends on view direction
 - bright near mirror configuration



Specular shading (Blinn-Phong)

- Close to mirror \Leftrightarrow half vector near normal
 - Measure “near” by dot product of unit vectors



$$\mathbf{h} = \text{bisector}(\mathbf{v}, \mathbf{l})$$

$$= \frac{\mathbf{v} + \mathbf{l}}{\|\mathbf{v} + \mathbf{l}\|}$$

$$L_s = k_s I \max(0, \cos \alpha)^p$$

$$= k_s I \max(0, \mathbf{n} \cdot \mathbf{h})^p$$

↑
specularly
reflected
light

↑
specular
coefficient

Phong model—plots

- Increasing n narrows the lobe

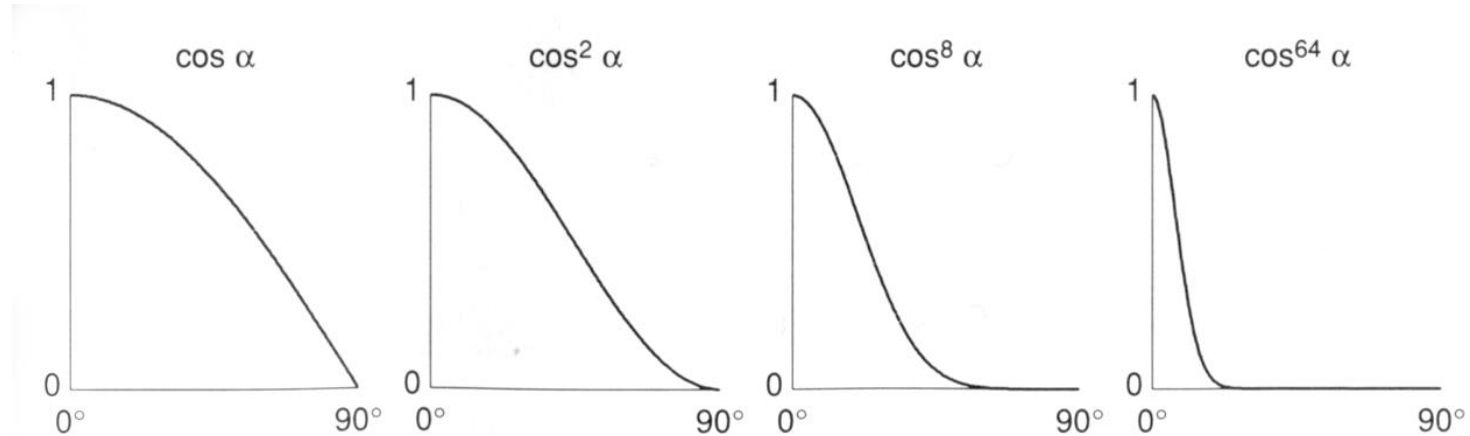
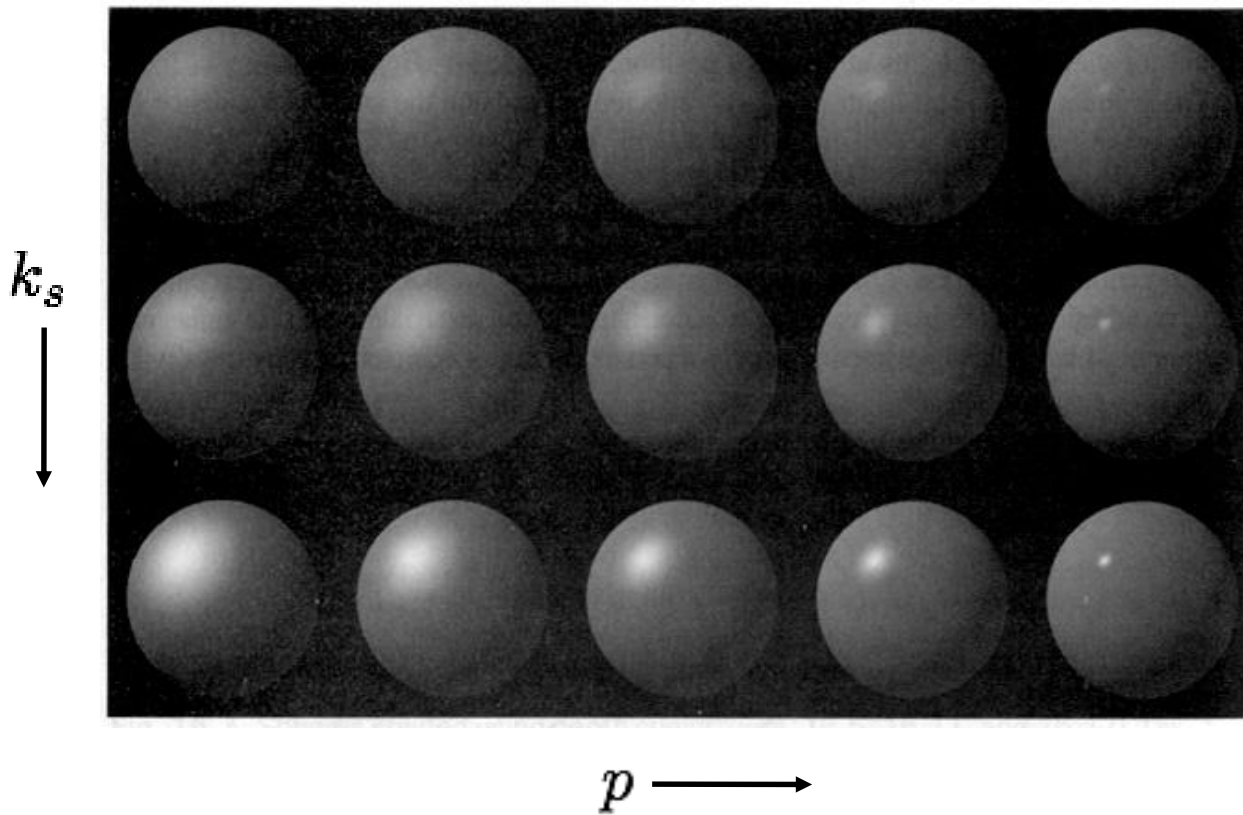
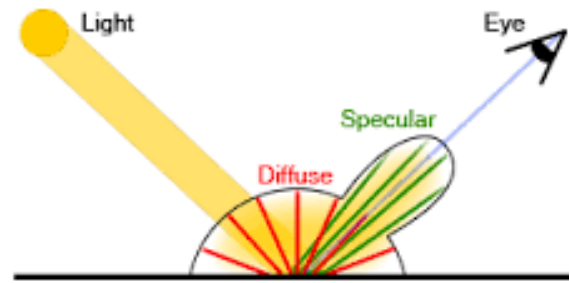


Fig. 16.9 Different values of $\cos^n \alpha$ used in the Phong illumination model.

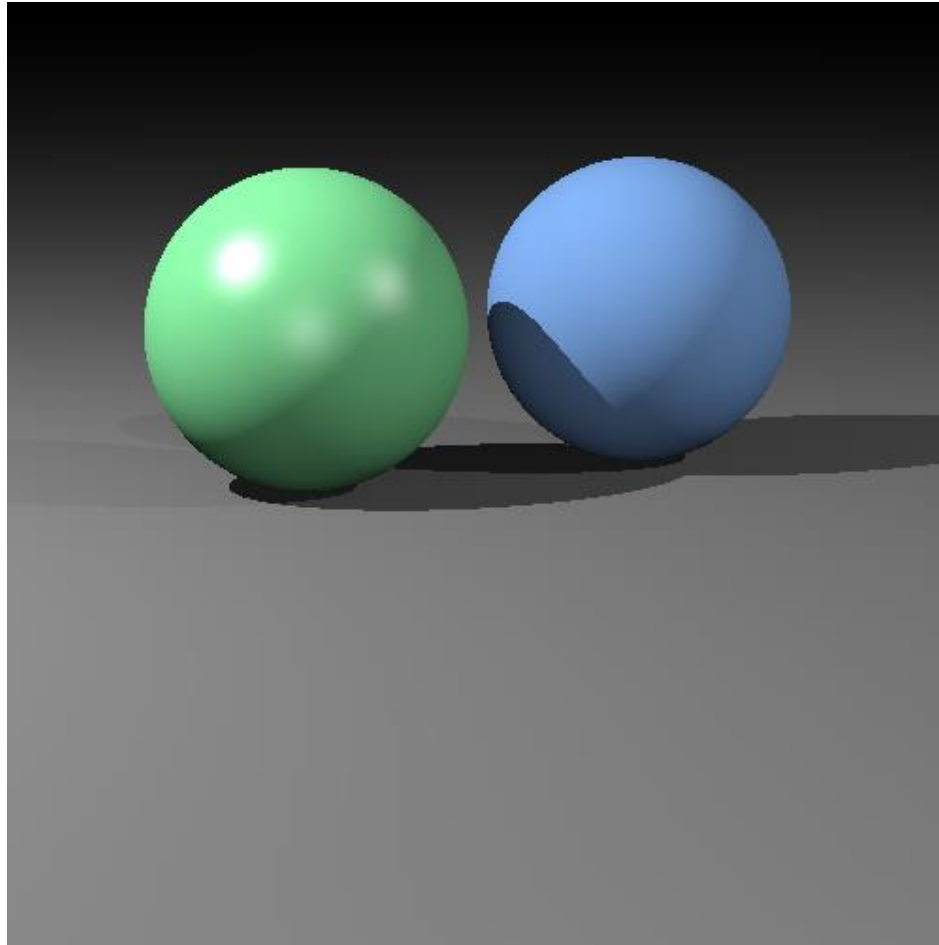
[Foley et al.]

Specular shading



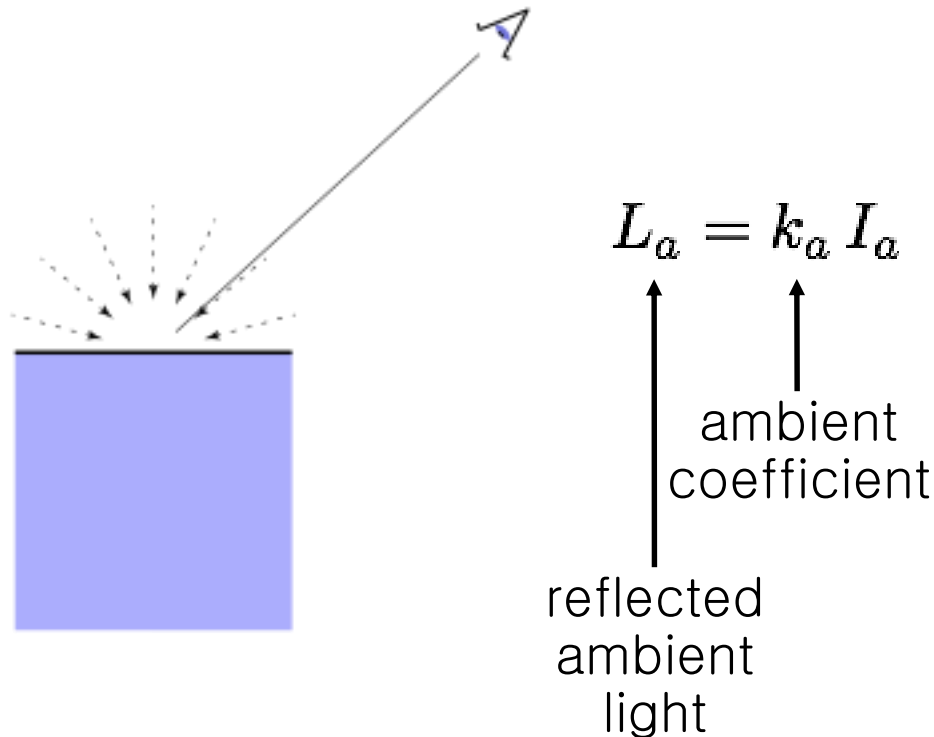
[Foley et al.]

Diffuse + Phong shading



Ambient shading

- Shading that does not depend on anything
 - add constant color to account for disregarded illumination and fill in black shadows



Putting it together

- Usually include ambient, diffuse, Phong in one model

$$L = L_a + L_d + L_s$$

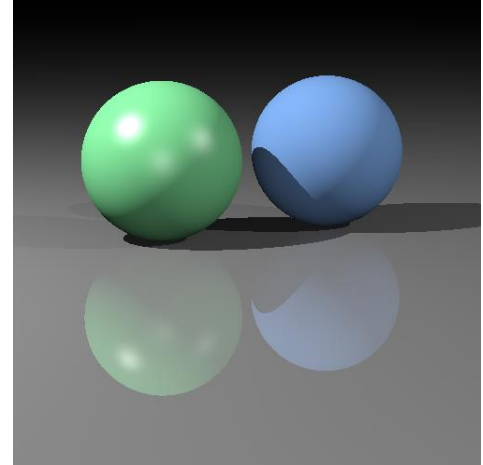
$$= k_a I_a + k_d I \max(0, \mathbf{n} \cdot \mathbf{l}) + k_s I \max(0, \mathbf{n} \cdot \mathbf{h})^p$$

- The final result is the sum over many lights

$$L = L_a + \sum_{i=1}^N [(L_d)_i + (L_s)_i]$$

$$L = k_a I_a + \sum_{i=1}^N [k_d I_i \max(0, \mathbf{n} \cdot \mathbf{l}_i) + k_s I_i \max(0, \mathbf{n} \cdot \mathbf{h}_i)^p]$$

Mirror reflection

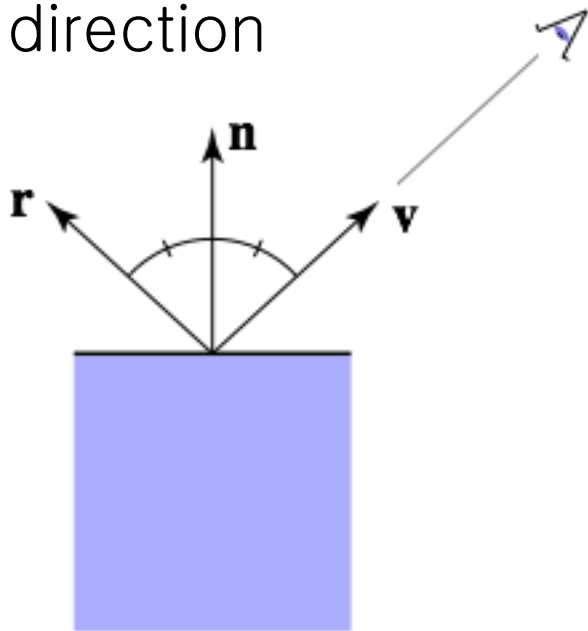


- Consider perfectly shiny surface
 - there isn't a highlight
 - instead there's a reflection of other objects
- Can render this using recursive ray tracing
 - to find out mirror reflection color, ask what color is seen from surface point in reflection direction
 - already computing reflection direction for Phong...
- “Glazed” material has mirror reflection and
$$\text{diffu}L = L_a + L_d + L_m$$

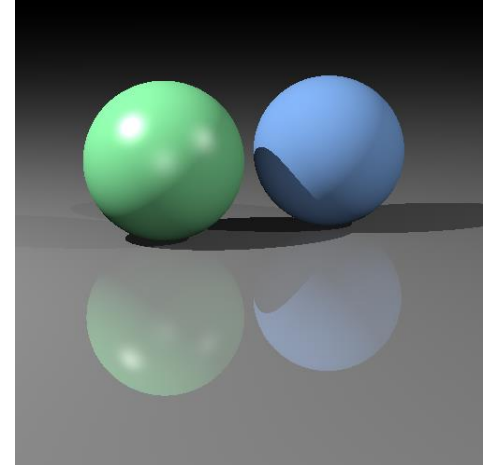
– where L_m is evaluated by tracing a new ray

Mirror reflection

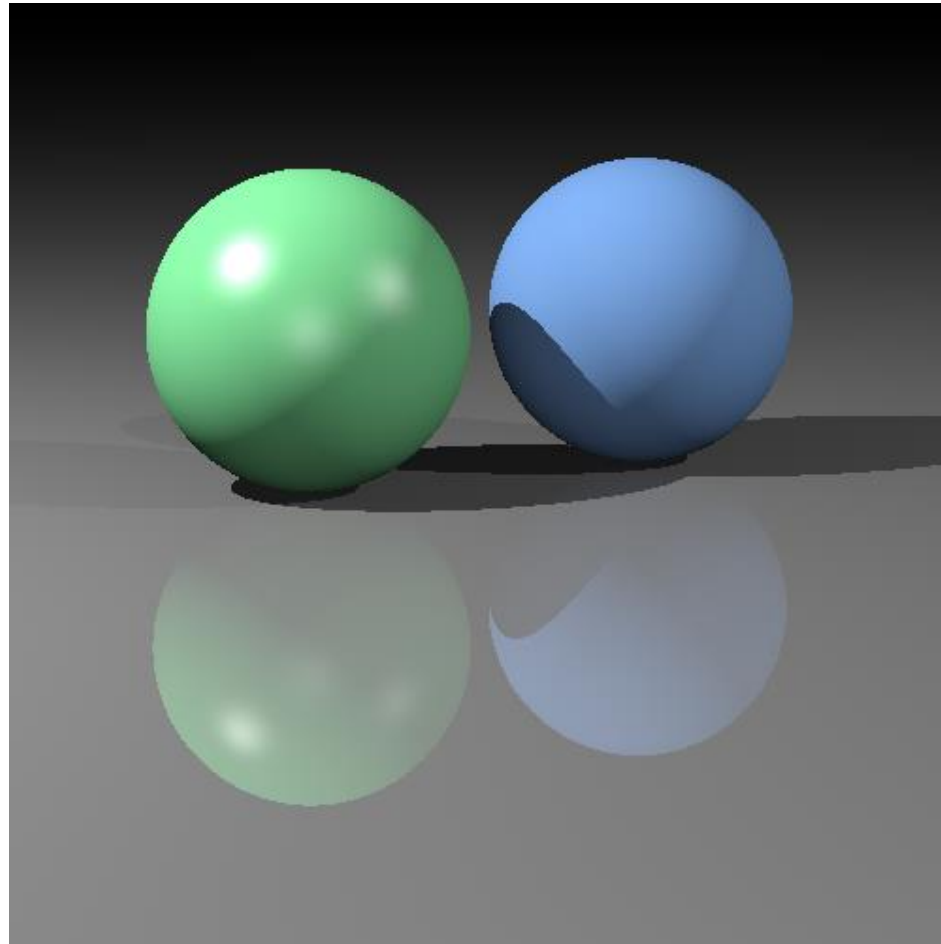
- Intensity depends on view direction
 - reflects incident light from mirror direction



$$\begin{aligned}\mathbf{r} &= \mathbf{v} + 2((\mathbf{n} \cdot \mathbf{v})\mathbf{n} - \mathbf{v}) \\ &= 2(\mathbf{n} \cdot \mathbf{v})\mathbf{n} - \mathbf{v}\end{aligned}$$



Diffuse + mirror reflection (glazed)



(glazed material on floor)